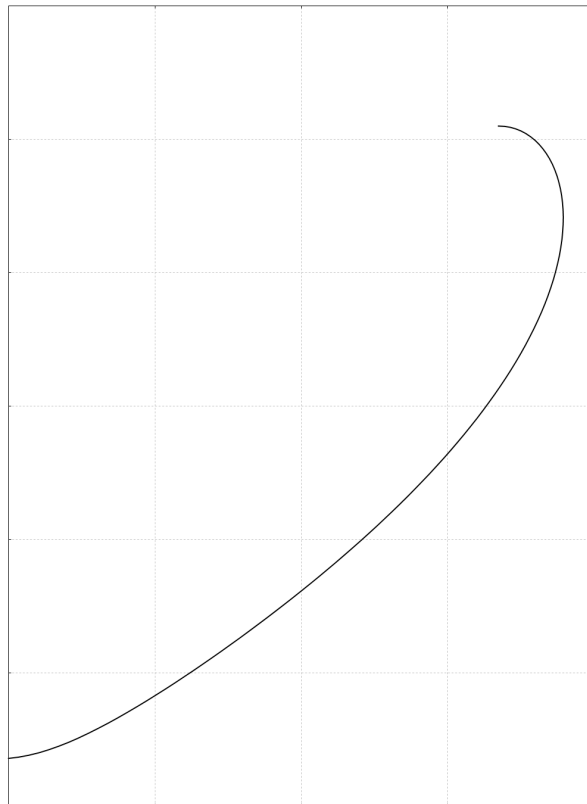


R-OSSE Acoustic Waveguide

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Introduction

In the previous work the OSSE ("OS-SE") waveguide formula was presented¹, extending the well-known Oblate Spheroidal (OS) waveguide by incorporating a smooth termination into a flat panel. While it proved the importance of the added gradual termination, due to its inherent half-space nature the usefulness was still somewhat limited - for a real-life use it is necessary to place such device into a finite baffle with an additional edge treatment which is not any more a part of its analytical description.

The now presented R-OSSE set of parametric equations goes a step further and defines a complete waveguide terminated into a free space by means of a convenient, self-containing analytical description. Such approach can be readily used e.g. in further optimization algorithms, CAD routines, etc.

The R-OSSE parametric description

In the following text we describe a profile of an axisymmetric waveguide as a set of coordinates $[x, y]$, where 'x' is the axial distance from the throat and 'y' is the distance of the profile point from the axis.

Because the OSSE has the form of a function $y(x)$, it can't describe shapes that fold back as the profile curve progresses (it can't have two different values for a single x). For this we need a parametric description in a form $[x, y] = [x(t), y(t)]$, where $x(t)$ and $y(t)$ are some functions of a new parameter 't'. Typically these functions are constructed so that the parameter 't' ranges from 0 to 1.

The functions used in the R-OSSE description are plotted on the Fig 1.

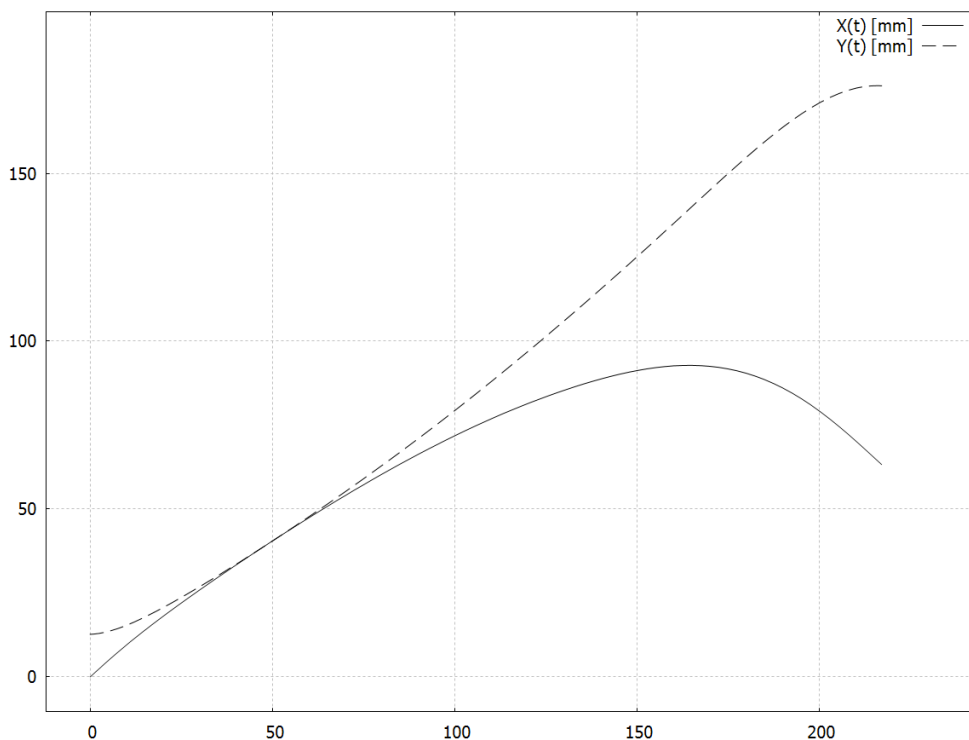


Fig. 1: R-OSSE $x(t), y(t)$ components

1 <http://www.at-horns.eu/release/OS-SE Waveguide.pdf>

The functions on Fig. 1 are constructed by means of two conic sections each. The function $x(t)$ is simply a difference of $x_1(t)$ and $x_2(t)$, a hyperbola and a parabola (Fig. 2). The function $y(t)$ is a weighted average of $y_1(t)$ and $y_2(t)$, both being hyperbolas, starting as y_2 and ending as y_1 (Fig. 3).

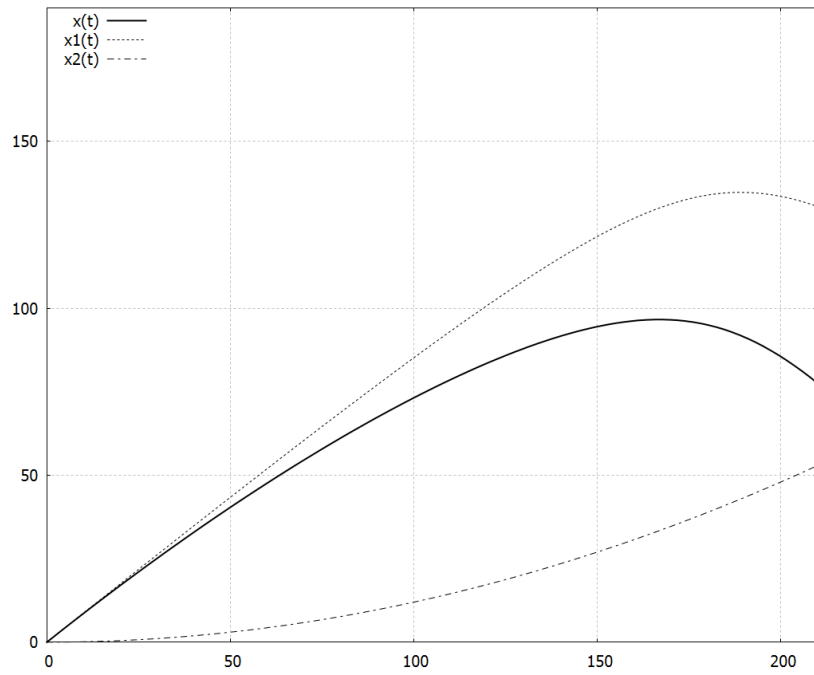


Fig. 2: $x(t)$ components

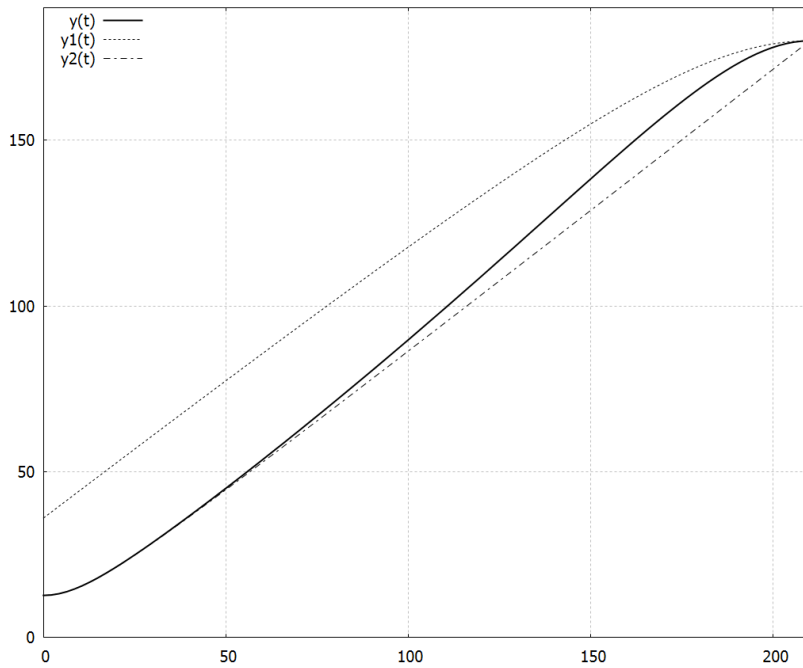


Fig. 3: $y(t)$ components

R-OSSE design formulae

Design Parameter	Description	unit/example
R	Waveguide outer radius	[mm]/190
a	Nominal coverage angle	[deg]/40
r ₀	Throat radius	[mm]/18
a ₀	Throat opening angle	[deg]/0
k	Throat expansion factor	1
r	Apex radius factor	0.3
m	Apex shift factor	0.8
b	Bending factor	0.3
q	Throat shape factor	3

Auxiliary constants

$$k_1 = (kr_0)^2$$

$$k_2 = 2kr_0 \tan(a_0)$$

$$k_3 = \tan^2(a)$$

$$L = \frac{\sqrt{k_2^2 - 4k_3(k_1 - (R+r_0(k-1))^2)} - k_2}{2k_3}$$

Core functions

$$x_1(t) = L(\sqrt{r^2+m^2} - \sqrt{r^2+(t-m)^2})$$

$$x_2(t) = b x_1(1)t^2$$

$$y_1(t) = \sqrt{k_1+k_2Lt+k_3L^2t^2} - r_0(k-1)$$

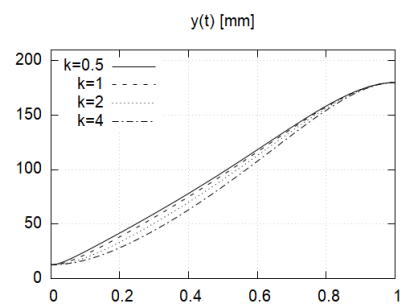
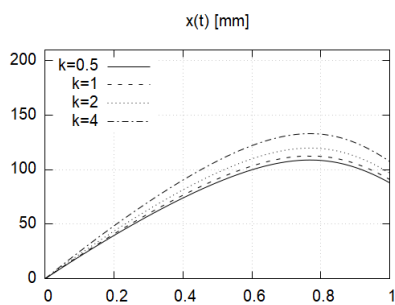
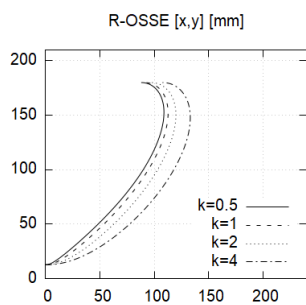
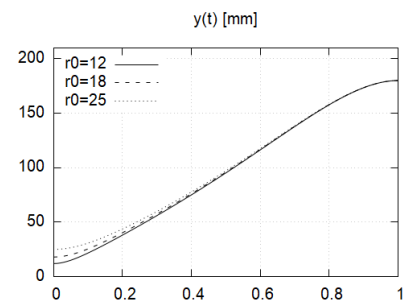
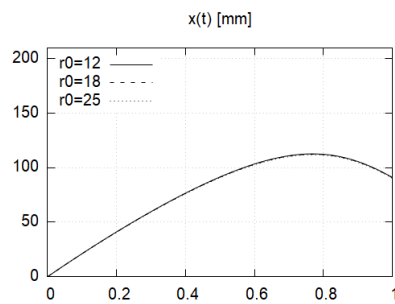
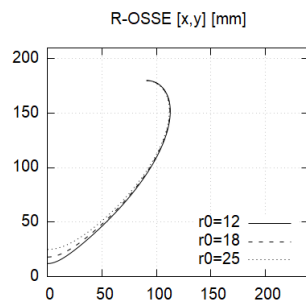
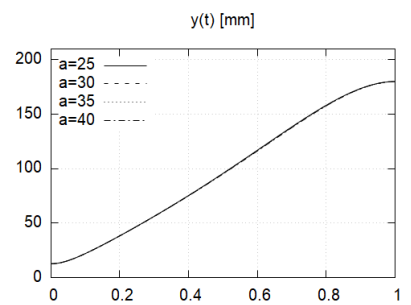
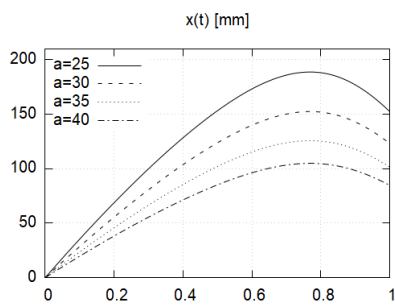
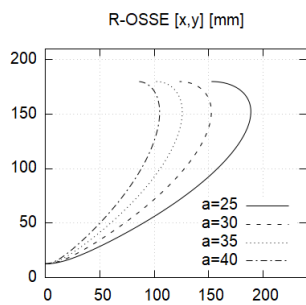
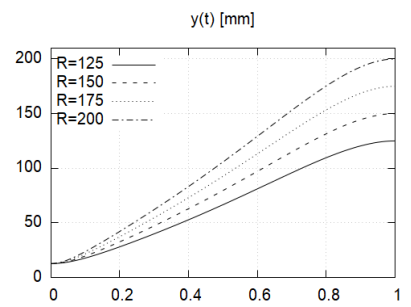
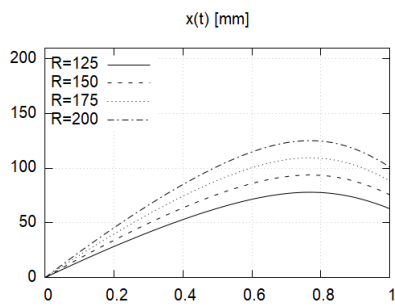
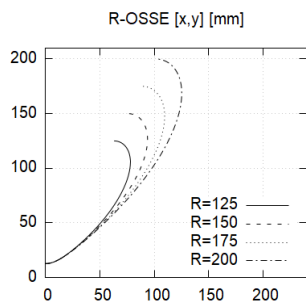
$$y_2(t) = R + L(1 - \sqrt{1+k_3(t-1)^2})$$

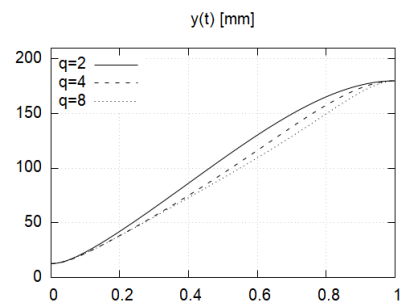
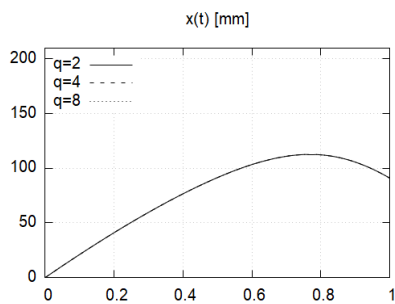
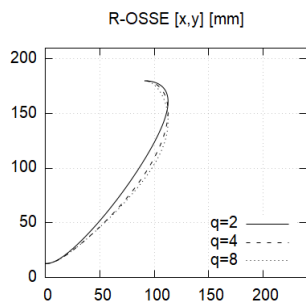
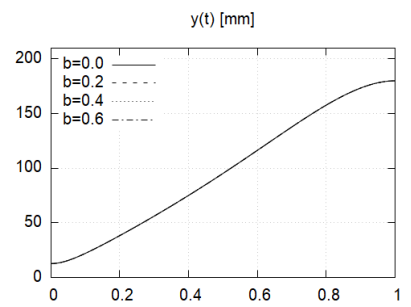
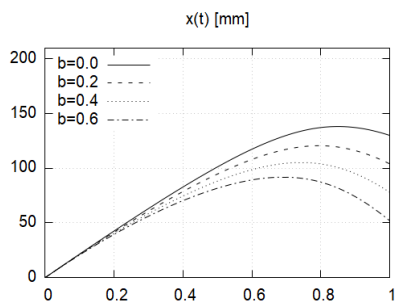
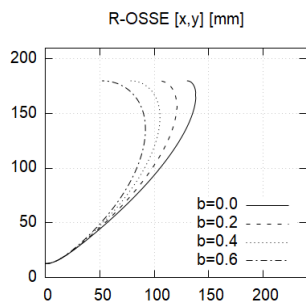
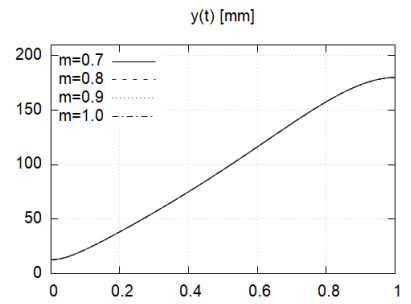
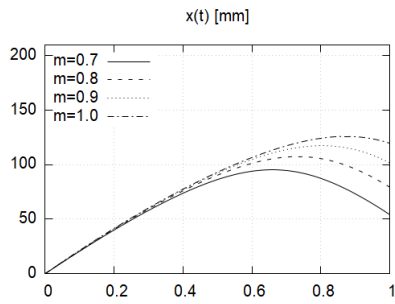
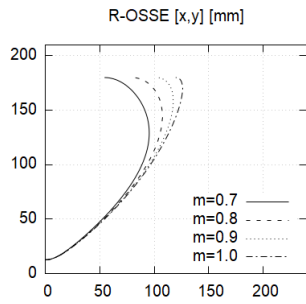
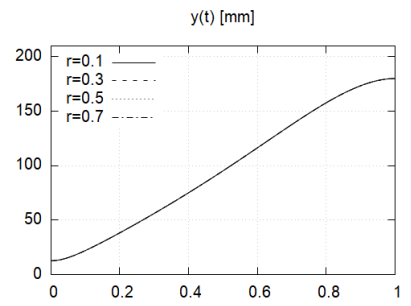
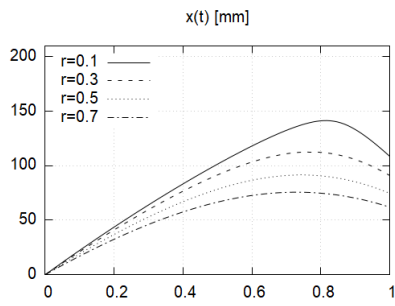
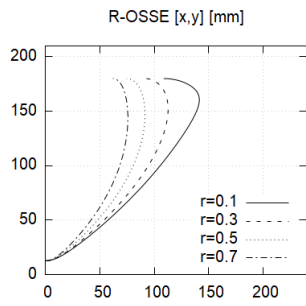
R-OSSE parametric equation

$$x(t) = x_1(t) - x_2(t)$$

$$y(t) = (1-t^q)y_1(t) + t^q y_2(t) \quad , \quad t \in \langle 0,1 \rangle$$

The following charts give an overview of the effect of each individual design parameter on the resulting shape.





Practical design example

R-OSSE parameters

A sample waveguide² with 25.4 mm (1") throat is presented, given by the parameters listed below. This set of values results in a device that is 260 mm (~10") wide and slightly less than 80 mm (~3") long - see Fig. 4.

$R = 130 \text{ mm}$	$k = 1.8$
$r_0 = 12.7 \text{ mm}$	$r = 0.3$
$a_0 = 7.5 \text{ deg}$	$b = 0.3$
$a = 39 \text{ deg}$	$m = 0.8$
	$q = 3.7$

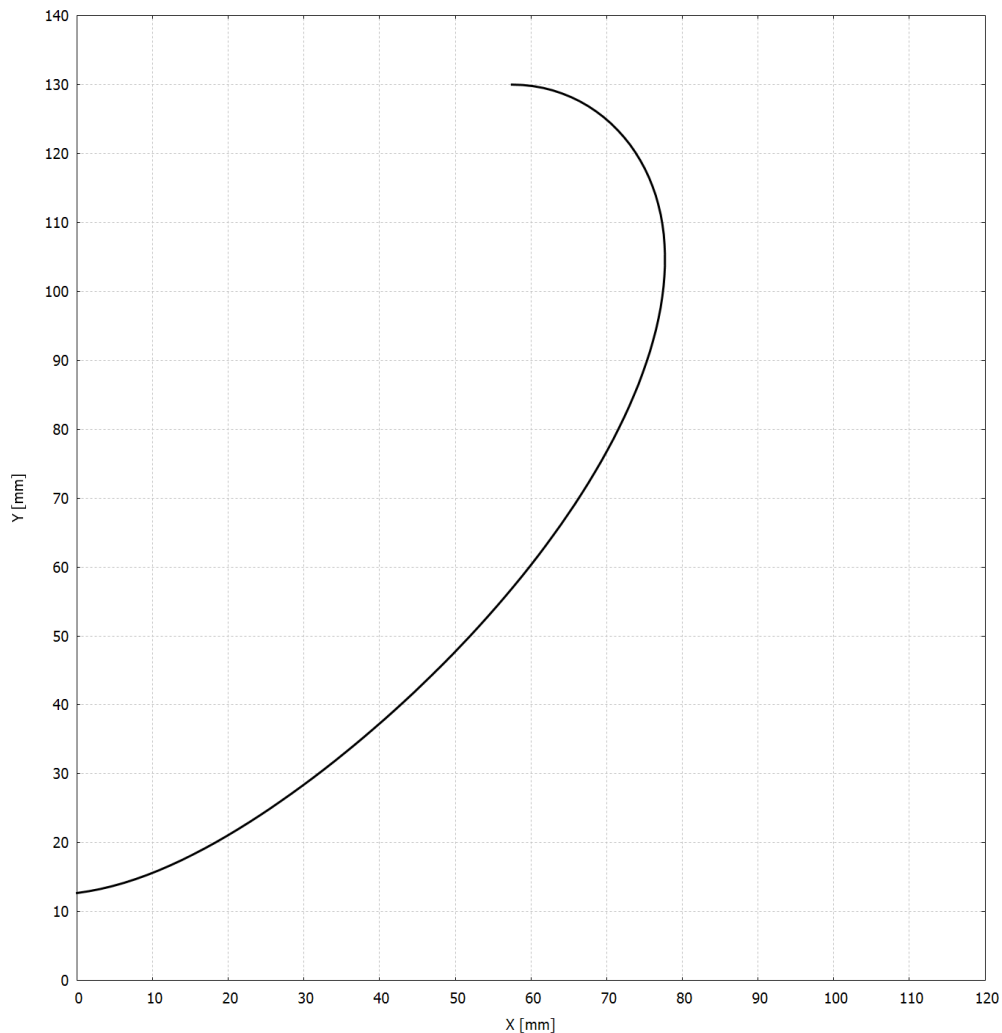
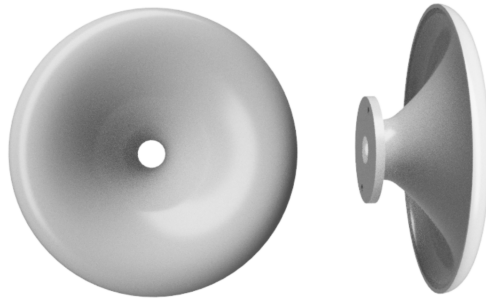


Fig. 4: Sample waveguide profile

² This is an approximation of a device that has been around for some time, known as "ST260", made freely available for audio hobbyists, at the time constructed using a different and more complicated approach.

BEM simulation

The above axisymmetric device was numerically simulated in free field - as free standing with 5 mm thick wall - via a boundary element method (BEM), using software ABEC by R&D Team³ (Mr. Joerg Panzer). 100 frequency points between 200 Hz and 20 kHz were used for the calculation. The results are presented in the following graphs.

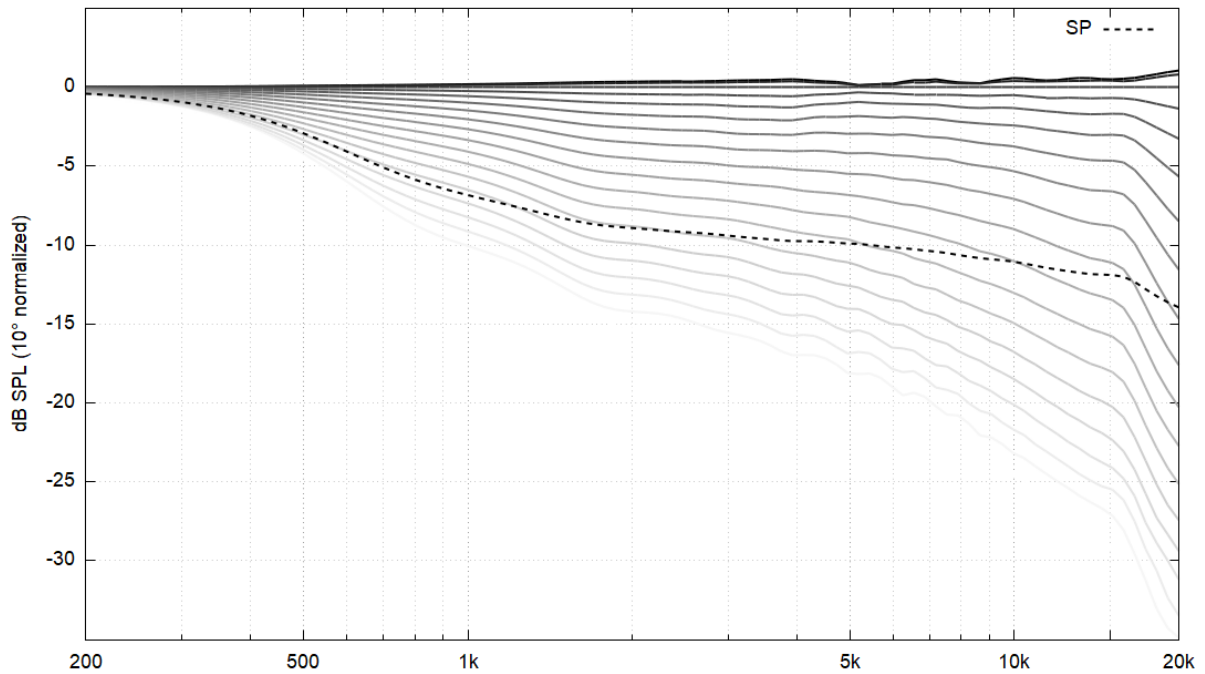


Fig. 5: BEM results - SPL polars, 0-90 deg / 5 deg step, 10 deg normalized

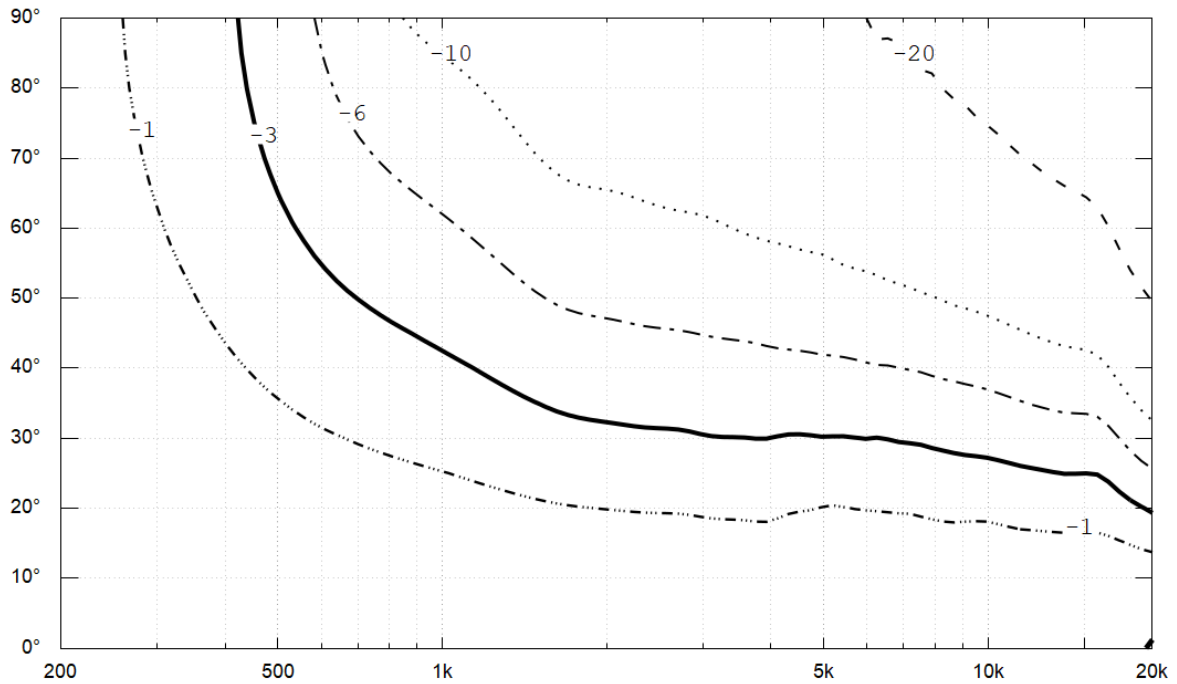


Fig. 6: BEM results - Polar map [dB SPL]

3 <http://www.randteam.de>

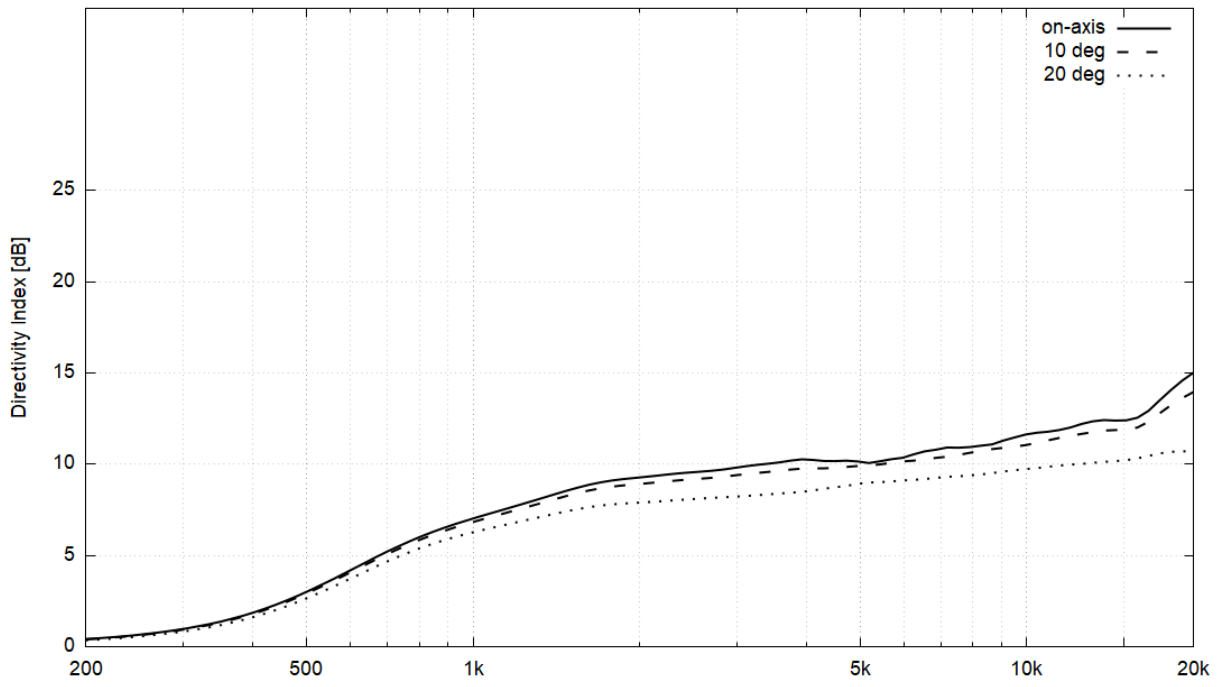


Fig. 7: BEM results - Directivity Index [dB]

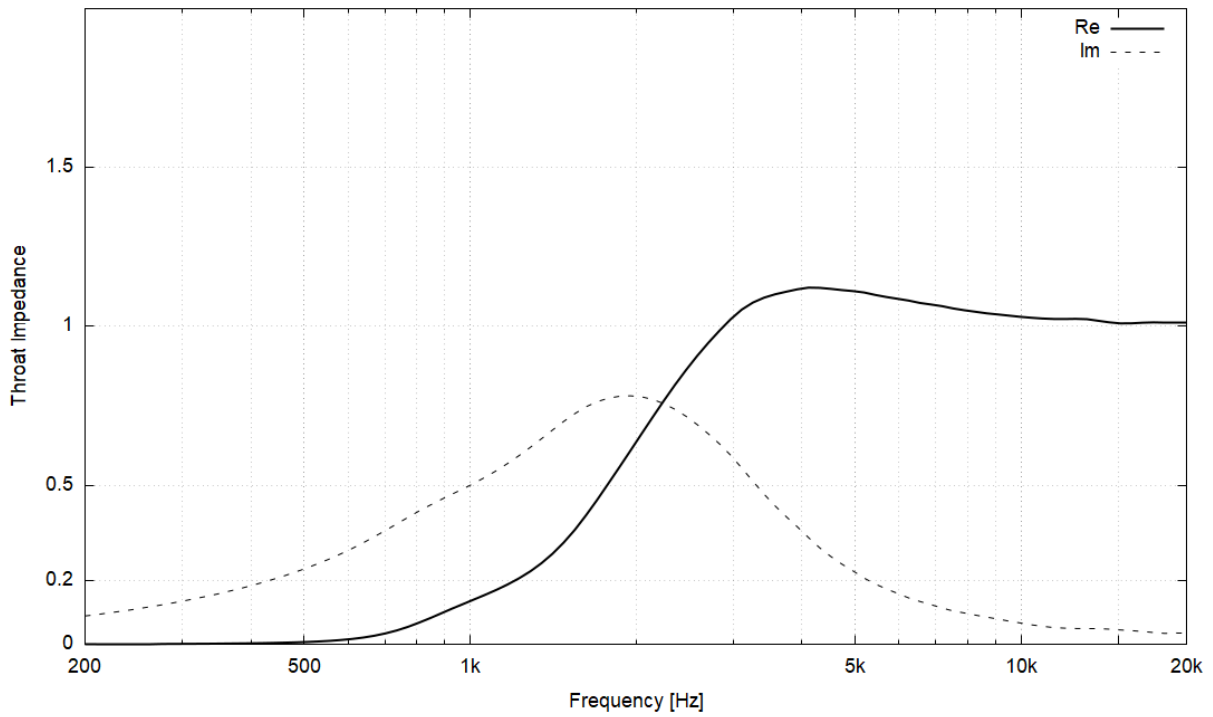


Fig. 8: BEM results - Throat acoustic impedance

Ath script code

For a reference, this is the Ath⁴ script code that was used to create the above waveguide BEM mesh.

```
R-OSSE = {
  R = 130
  r0 = 12.7
  a0 = 7.5
  a = 39
  k = 1.8
  r = 0.3
  b = 0.3
  m = 0.8
  q = 3.7
}

Mesh.LengthSegments = 60
Mesh.AngularSegments = 8
Mesh.SubdomainSlices =
Mesh.WallThickness = 5

Source.Shape = 1

ABEC.SimType = 2
ABEC.SimProfile = 0
ABEC.MeshFrequency = 43000
ABEC.NumFrequencies = 100
ABEC.Abscissa = 1
ABEC.f1 = 200
ABEC.f2 = 20000

ABEC.Polars:SPL = {
  MapAngleRange = 0,180,37
  NormAngle = 10
}

Output.ABECProject = 1
Output.STL = 0

Report = {
  Title = ST260-ROSSE
  Width = 1600
  Height = 1000
}
```